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Education

IIT Guwahati, B.Tech Major in Electronics and Electrical Engineering CGPA: 8.11/10 2016 - 2020 Guwahati, India IIT Guwahati, B.Tech Minor in Computer Sciences and Engineering 2017 - 2019 Guwahati, India CGPA: 8.5/10

Skills_

Robotics ROS, OpenCV, Stereo Vision, Visual Odometry

Programming Python, C++/C, Java, C#*

Hardware Arduino, Raspberry-Pi, IMU Sensor, Camera, RGBD Camera, Actuators And Encoders Machine Learning Decision Trees & Random Forest, SVM, Neural Networks, CNNs, GANs*, RNNs*

Tools/Packages Keras, Tensorflow, Unity3D*, Pytorch, Numpy, MatplotLib, Pandas, Gazebo*

Work Experience

Strato IT, Protec Inc. Anyang, South Korea

ROBOTICS & DEEP LEARNING INTERN

May 2019 - Jul. 2019

- Implemented multiple Deep Learning models for disparity estimation of stereo vision in ease to use packaged python modules.
- · Wrote ROS packages to test present hardware and software techniques in visual and inertial odometry.

Bengaluru, India **AppSecure**

API Developer & Machine Learning Intern

May. 2018 - Jul. 2018

- Implemented a combined package software for active sub-domain and port scanning for web-servers.
- Using the same trained a model to predict the presence of a word in the web-server directory or sub-domain.

Soil Nutrient Estimation Robot

IIT Guwahati India

7TH INTER IIT TECHMEET | 5 MEMBER TEAM | ☑ GITHUB

Nov. 2018 - Dec. 2018

- The robot collected soil sample and measured nitrogen-phosphorus-potassium content of every 1 sq. meter of farmland respectively.
- It performed Colorimtery using a LDR and RGB-LED on soil samples to estimate accurate fertilizer requirement for different farmland patches.

Eye In The Sky 7TH INTER IIT TECHMEET | 3 MEMBER TEAM | ① GITHUB

IIT Guwahati, India Nov. 2018 - Dec. 2018

• Achieved remote sensing of satellite data using deep learning semantic segmentation.

• Implemented 4 different algorithms UNet, PSPNet both with RGB Channels and One-Hot encoded channels.

ARLE(Automated Robot for Library Enchancement)

IIT Guwahati, India

41 LABS, IIT GUWAHATI | 9 MEMBER TEAM | 🖸 GITHUB | 希 HOMEPAGE | 🛗 YOUTUBE

Jul. 2017 - PRESENT

- Built a four wheeled robot which can perform SLAM and visual localization in library environment according to any specified book.
- Wrote a ROS package to achieve the visual odometry and mapping mentioned using LIDAR and RGBD Camera.

Technologies for Soldier Support- Health Monitoring System

IIT Guwahati, India

6TH INTER IIT TECHMEET | 3 MEMBER TEAM

Dec. 2017 - Jan. 2018

- Designed a suit using MPU9250, Temperature and Heart Rate Sensor to predict the physical state of ability and inability of a soldier.
- Being lightweight and built with an ESP8266 it transmitted live condition of the soldiers to base station.

Key Courses_

Electrical & Electronics Advanced Control Systems, Probability and Random Processes, Digital Systems, Microprocessors Computer Science Game Theory, Operating Systems, Computer Architecture, Data Structures, Algorithms, Networks

Robotics ROS Tutorials in Python, A.I. for Robotics, Deep Learning for Self-Driving Cars

Mathematics Linear Algebra, Basic Calculus, Discrete Maths

Machine Learning Basic Machine Learning, Artifical Neural Networks, Convolutional Neural Network & Computer Vision

Awards_

2018	Bronze Medal, Tata Centre for Technological Development Challenge, 7th Inter IIT TechMeet, IIT Bombay	Bombay, India
2017	Bronze Medal, Technologies for Soldier Support, 6th Inter IIT TechMeet, IIT Madras	Madras, India
2017	1st Position for 2 consecutive years. Electrovate Inter-Hostel Tech-Innovation Event IIT Guwahati	Guwahati India

Positions of Responsibility _____

Apr. 2018 - Apr. 2019	Secretary, Robotics Club, IIT Guwahati	Guwahati, India
Feb.2018 - Apr. 2019	Co-Founder and Manager, IITG.ai, IIT Guwahati	Guwahati, India
Apr. 2017 - Apr. 2018	Technical Secretary, Umiam Hostel, Hostel Affairs Board, IIT Guwahati	Guwahati, India
Apr. 2017 - Apr. 2019	Team Head , ARLE, 4i Labs, IIT Guwahati	Guwahati, India